#### **B. E. ELECTRICAL AND ELECTRONICS ENGINEERING** Choice Based Credit System (CBCS) and Outcome Based Education (OBE) **SEMESTER - IV ELECTRIC MOTORS** Course Code **18EE44** CIE Marks 40 Number of Lecture Hours/Week SEE Marks 3:0:0 60 Credits 03 Exam Hours 03 **Course Learning Objectives:** • To study the constructional features of Motors and select a suitable drive for specific application. • To study the constructional features of Three Phase and Single phase induction Motors. • To study different test to be conducted for the assessment of the performance characteristics of motors. • To study the speed control of motor by a different methods. • Explain the construction and operation of Synchronous motor and special motors. Module-1 DC Motors: Classification, Back emf, Torque equation, and significance of back emf. Characteristics of shunt, series & compound motors. Speed control of shunt, series and compound motors. Application of motors. DC motor starters - 3 point and 4 point. Losses and Efficiency- Losses in DC motors, power flow diagram, efficiency, condition for maximum efficiency. Module-2 Testing of DC Motors: Direct & indirect methods of testing of DC motors-Brake test, Swinburne's test, Retardation test, Hopkinson's test, Field's test, merits and demerits of tests. Three Phase Induction Motors: Review of concept and generation of rotating magnetic field, Principle of operation, construction, classification and types; squirrel-cage, slip-ring (No question shall be set from the review portion). Slip, Torque equation, torque-slip characteristic covering motoring, generating and braking regions of operation, Maximum torque, significance of slip. Module-3 Performance of Three-Phase Induction Motor: Phasor diagram of induction motor on no-load and on load, equivalent circuit, losses, efficiency, No-load and blocked rotor tests. Performance of the motor from the circle diagram and equivalent circuit. Cogging and crawling. High torque rotors-double cage and deep rotor bars. Equivalent circuit and performance evaluation of double cage induction motor. Induction motor working as induction generator. Module-4 Starting and Speed Control of Three-Phase Induction Motors: Need for starter. Direct on line, Star-Delta and autotransformer starting. Rotor resistance starting. Speed control by voltage, frequency, and rotor resistance methods Single-Phase Induction Motor: Double revolving field theory and principle of operation. Construction and operation of split-phase, capacitor start, capacitor run, and shaded pole motors. Comparison of single phase motors and applications. Module-5 Synchronous Motor: Principle of operation, phasor diagrams, torque and torque angle, Blondel diagram, effect of change in load, effect of change in excitation, V and inverted V curves. Synchronous condenser, hunting and damping. Methods of starting synchronous motors. Other Motors: Construction and operation of Universal motor, AC servomotor, Linear induction motor and stepper motors. ■ **Course Outcomes:** At the end of the course the student will be able to: Explain the construction, operation and classification of DC Motor, AC motor and Special purpose • motors. Describe the performance characteristics & applications of Electric motors. Demonstrate and explain the methods of testing of DC machines and determine losses and efficiency. Control the speed of DC motor and induction motor. Explain the starting methods, equivalent circuit and phasor diagrams, torque angle, effect of change in excitation and change in load, hunting and damping of synchronous motors.

# **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 20 marks.
- There will be 2 full questions (with a maximum of three sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

Text Books:				
1	Electric Machines	D. P. Kothari, I. J. Nagrath	McGraw Hill	4th edition, 2011
2	Theory of Alternating Current Machines	Alexander Langsdorf	McGraw Hill	2nd Edition, 2001
3	Electric Machines	Ashfaq Hussain	Dhanpat Rai & Co	2nd Edition, 2013
Reference Books:				
1	Electrical Machines, Drives and Power systems	Theodore Wildi	Pearson	6th Edition, 2014
2	Electrical Machines	M.V. Deshpande	PHI Learning	2013
3	Electric Machinery and Transformers	Bhag S Guru at el	Oxford University Press	3 <sup>rd</sup> Edition, 2012
4	Electric Machinery and Transformers	Irving Kosow	Pearson	2rd Edition, 2012
5	Principles of Electric Machines and	P.C.Sen	Wiley	2nd Edition, 2013
6	Electric Machines	R.K. Srivastava	Cengage Learning	2nd Edition,2013
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# B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - V

MICROCONTROLLER				
Course Code	18EE52	CIE Marks	40	
Number of Lecture Hours/Week (L:T:P)	3:2:0	SEE Marks	60	
Credits	04	Exam Hours	03	

### **Course Learning Objectives:**

- To explain the internal organization and working of Computers, microcontrollers and embedded processors.
- Compare and contrast the various members of the 8051 family.
- To explain the registers of the 8051 microcontroller, manipulation of data using registers and MOV instructions.
- To explain in detail the execution of 8051 Assembly language instructions and data types
- To explain loop, conditional and unconditional jump and call, handling and manipulation of I/O instructions.
- To explain different addressing modes of 8051, arithmetic, logic instructions, and programs.
- To explain develop 8051C programs for time delay, I/O operations, I/O bit manipulation, logic,

# Module-1

**8051 Microcontroller Basics:** Inside the Computer, Microcontrollers and Embedded Processors, Block Diagram of 8051, PSW and Flag Bits, 8051 Register Banks and Stack, Internal Memory Organization of 8051, IO Port Usage in 8051, Types of Special Function Registers and their uses in 8051, Pins Of 8051. Memory Address Decoding, 8031/51 Interfacing With External ROM And RAM.8051 Addressing

# Modes.

Module-2

Assembly Programming and Instruction of 8051: Introduction to 8051 assembly programming, Assembling and running an 8051 program, Data types and Assembler directives, Arithmetic, logic instructions and programs, Jump, loop and call instructions, IO port programming.

# Module-3

**8051 Programming in C:** Data types and time delay in 8051C, IO programming in 8051C, Logic operations in 8051 C, Data conversion program in 8051 C, Accessing code ROM space in 8051C, Data serialization using 8051C

**8051 Timer Programming in Assembly and C:** Programming 8051 timers, Counter programming, Programming timers 0 and 1 in 8051 C. ■

Module-4

**8051 Serial Port Programming in Assembly and C:** Basics of serial communication, 8051 connection to RS232, 8051 serial port programming in assembly, serial port programming in 8051 C.

**8051 Interrupt Programming in Assembly and C:** 8051 interrupts, Programming timer, external hardware, serial communication interrupt, Interrupt priority in 8051/52, Interrupt programming in C. ■ **Module-5** 

Interfacing: LCD interfacing, Keyboard interfacing.

**ADC, DAC and Sensor Interfacing:** ADC 0808 interfacing to 8051, Serial ADC Max1112 ADC interfacing to 8051, DAC interfacing, Sensor interfacing and signal conditioning.

Motor Control: Relay, PWM, DC and Stepper Motor: Relays and opt isolators, stepper motor interfacing, DC motor interfacing and PWM.

8051 Interfacing with 8255: Programming the 8255, 8255 interfacing, C programming for 8255. ■

Course Outcomes: At the end of the course the student will be able to:

- Outline the 8051 architecture, registers, internal memory organization, addressing modes.
- Discuss 8051 addressing modes, instruction set of 8051, accessing data and I/O port programming.
- Develop 8051C programs for time delay, I/O operations, I/O bit manipulation, logic and arithmetic operations, data conversion and timer/counter programming.
- Summarize the basics of serial communication and interrupts, also develop 8051 programs for serial data communication and interrupt programming.
- Program 8051 to work with external devices for ADC, DAC, Stepper motor control, DC motor control, Elevator control.■

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- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

### **Text Book**

1	The 8051 Microcontroller and Embedded Systems Using Assembly and C	Muhammad Ali Mazadi	Pearson	2 <sup>nd</sup> Edition, 2008.
Reference Books				
1	The 8051 Microcontroller	Kenneth Ayala	Cengage Learning	3 <sup>rd</sup> Edition, 2005
2	The 8051 Microcontroller and Embedded Systems	Manish K Patel	McGraw Hill	2014
3	Microcontrollers: Architecture, Programming, Interfacing and System Design	Raj Kamal	Pearson	1 <sup>st</sup> Edition, 2012

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE)				
SEMESTER - V				
P	OWER ELEC	TRONICS		
Course Code	18EE53	CIE Marks	40	
Number of Lecture Hours/Week (L:T:P)	3:2:0	SEE Marks	60	
Credits	04	Exam Hours	03	
<ul> <li>Course Learning Objectives:</li> <li>To give an overview of applications their switching characteristics.</li> <li>To avalain power diode characteristic</li> </ul>	power electron	ics, different types of powe	r semiconductor devices,	
<ul> <li>To explain power diode characteristics, types, their operation and the effects of power diodes on RL circuits.</li> <li>To explain the techniques for design and analysis of single phase diode rectifier circuits.</li> <li>To explain different power transistors, their steady state and switching characteristics andimitations.</li> <li>To explain different types of Thyristors, their gate characteristics and gate control requirements.</li> <li>To explain the design, analysis techniques, performance parameters and characteristics of controlled rectifiers, DC- DC, DC -AC converters and Voltage controllers.</li> </ul>				
Module-1				
Introduction: Applications of Power Electronics, Types of Power Electronic Circuits, Peripheral Effects, Characteristics and Specifications of Switches. Power Diodes: Introduction, Diode Characteristics, Reverse Recovery Characteristics, Power Diode Types, Silicon Carbide Diodes, Silicon Carbide Schottky Diodes, Freewheeling diodes ,Freewheeling diodes with RL load. Diode Rectifiers: Introduction, Diode Circuits with DC Source connected to R and RL load, Single-Phase				
Tun Wave Recurrers with R load ; Shigh	Thuse Tun We	with Rectifier with RE Load		
Power Transistors: Introduction, Power MOSFETs – Steady State Characteristics, Switching Characteristics Bipolar Junction Transistors – Steady State Characteristics, Switching Characteristics, Switching Limits, IGBTs, MOSFET Gate Drive, BJT Base Drive, Isolation of Gate and Base Drives, Pulse transformers and Opto-couplers.∎ T1Module-3Thyristors: Introduction, Thyristor Characteristics, Two-Transistor Model of Thyristor, Thyristor Turn-				
On, Thyristor Turn-Off, A brief study on Thyristor Types, Series Operation of Thyristors, Parallel Operation of Thyristors, $di/dt$ Protection, $dv/dt$ Protection, DIACs, Thyristor Firing Circuits, Unijunction Transistor. <b>T</b> 1				
Module-4				
<b>Controlled Rectifiers:</b> Introduction, Single phase half wave circuit with RL Load, Single phase half wave circuit with RL Load and Freewheeling Diode, Single phase half wave circuit with RLE Load, Single-Phase Full Converters with RLE Load, Single-Phase Dual Converters, Principle of operation of Three- Phase duel Converters.				
Full-Wave Controllers with Resistive Loads, Single- Phase Full-Wave Controllers with Inductive Loads,				
1100-11000-100-00000000000000000000000				
MOQUE-5 DC DC Compartons Interchection minimized of star design of the main design of the second star of the second star				
performance parameters. DC-DC converter classification				
<b>DC-AC</b> Converters: Introduction, principle of operation single phase bridge inverters, three phase bridge				
inverters, voltage control of single phase i	nverters, Harm	onic reductions, Current so	ource inverters.■ T1	
<ul> <li>Course Outcomes: At the end of the course the student will be able to:</li> <li>To give an overview of applications power electronics, different types of power semiconductor devices, their switching characteristics, power diode characteristics, types, their operation and the effects of power diodes on RL circuits.</li> <li>To explain the techniques for design and analysis of single phase diode rectifier circuits.</li> </ul>				

- To explain different power transistors, their steady state and switching characteristics and limitations.
- To explain different types of Thyristors, their gate characteristics and gate control requirements.
- To explain the design, analysis techniques, performance parameters and characteristics of controlled rectifiers, DC- DC, DC -AC converters and Voltage controllers. ■

### Question paper pattern:

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- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

Text Book						
1	Power Electronics: Circuits Devices and Applications	Mohammad H Rashid,	Pearson	4th Edition, 2014		
Refe	Reference Books					
1	Power Electronics	P.S. Bimbhra	Khanna Publishers	5th Edition, 2012		
2	Power Electronics: Converters, Applications	Ned Mohan et al	Wiley	3rd Edition, 2014		
3	Power Electronics	Daniel W Hart	McGraw Hill	1 <sup>st</sup> Edition, 2011		
4	Elements of Power Electronics	Philip T Krein	Oxford	Indian Edition, 2008		